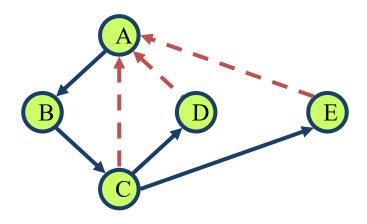
### **Depth-First Search**



## **Outline and Reading**

Definitions (6.1)

- Subgraph
- Connectivity
- Spanning trees and forests

Depth-first search (6.3.1)

- Algorithm
- Example
- Properties
- Analysis

Applications of DFS (6.5)

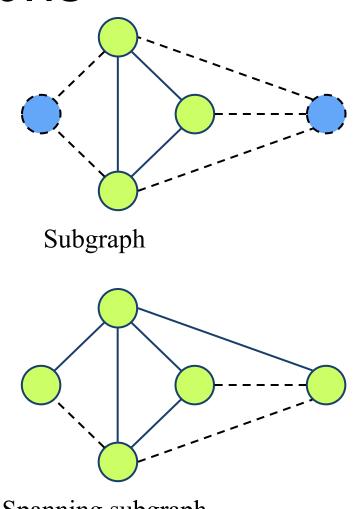
- Path finding
- Cycle finding

## Subgraphs

A subgraph S of a graph G is a graph such that

- the vertices of S are a subset of the vertices of G
- the edges of S are a subset of the edges of G

A spanning subgraph of G is a subgraph that contains all the vertices of G

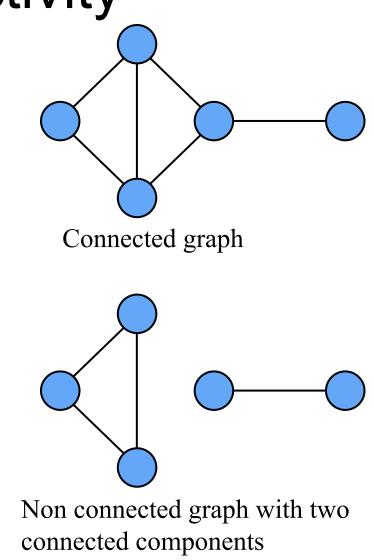


Spanning subgraph

### Connectivity

A graph is connected if there is a path between every pair of vertices

A connected component of a graph G is a maximal connected subgraph of G

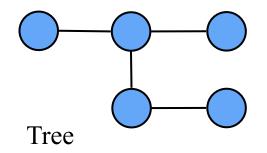


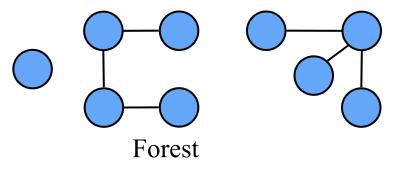
## **Trees and Forests**

- A (free) tree is an undirected graph T such that
  - T is connected
  - T has no cycles

This definition of tree is different from the one of a rooted tree

- A forest is an undirected graph without cycles
- The connected components of a forest are trees

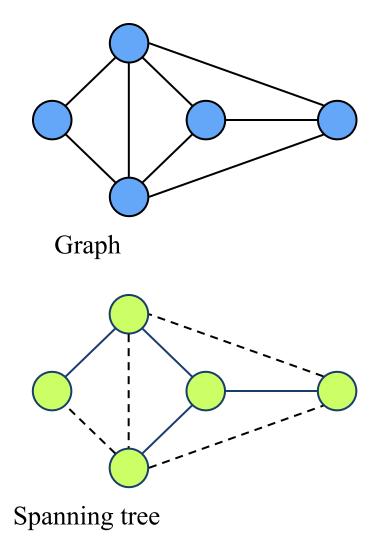




# **Spanning Trees and Forests**

A spanning tree of a connected graph is a spanning subgraph that is a tree

- A spanning tree is not unique unless the graph is a tree
- Spanning trees have applications to the design of communication networks
- A spanning forest of a graph is a spanning subgraph that is a forest



## **Depth-First Search**

- Depth-first search (DFS) is a general technique for traversing a graph. A DFS traversal of a graph G
  - visits all the vertices and edges of G
  - determines whether G is connected
  - computes the connected components of G
  - computes a spanning forest of G
- DFS on a graph with *n* vertices and *m* edges takes O(n + m) time
- DFS can be further extended to solve other graph problems
  - find and report a path between two given vertices
  - find a cycle in the graph
- Depth-first search is to graphs what Euler tour is to binary trees

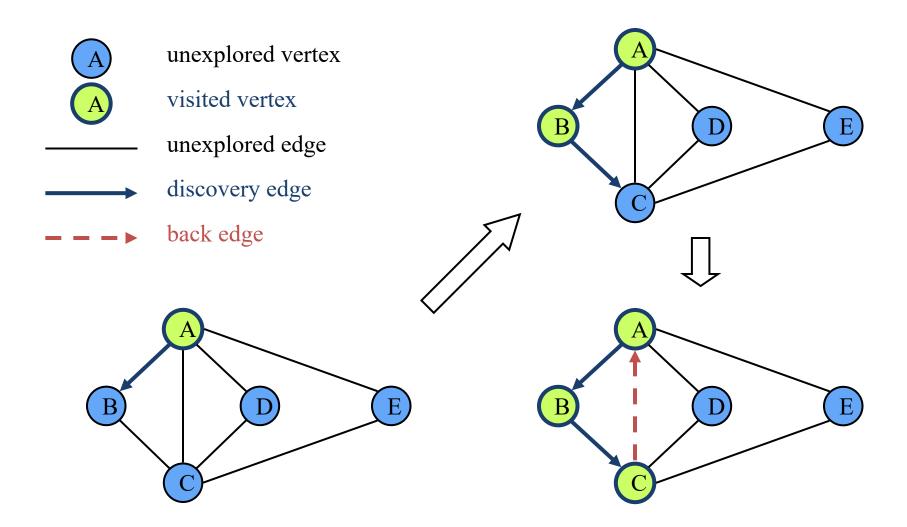
# **DFS** Algorithm

The algorithm uses a mechanism for setting and getting "labels" of vertices and edges.

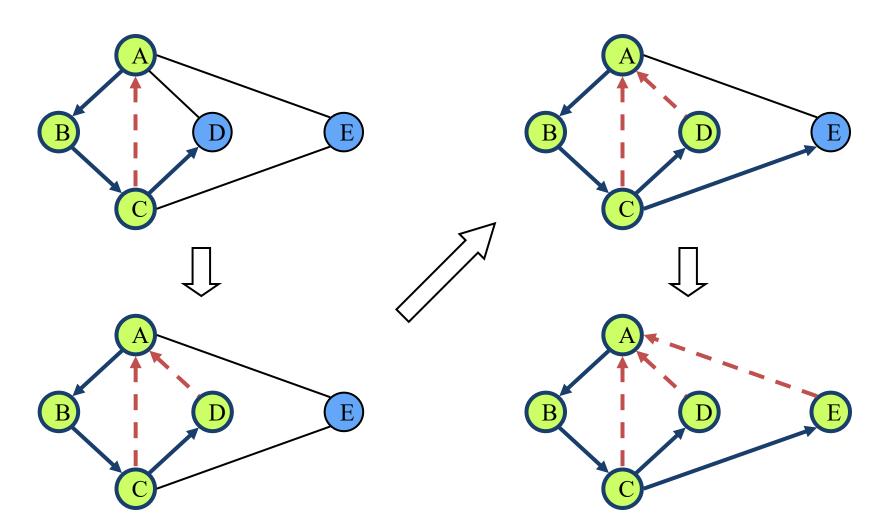
```
Algorithm DFS(G)
 Input graph G
 Output labeling of the edges of G
     as discovery edges and
    back edges
for all u \in G.vertices()
 setLabel(u, UNEXPLORED)
for all e \in G.edges()
 setLabel(e, UNEXPLORED)
for all v \in G.vertices()
 if getLabel(v) = UNEXPLORED
    DFS(G, v)
```

#### Algorithm DFS(G, v)**Input** graph *G* and a start vertex *v* of *G* Output labeling of the edges of G in the connected component of vas discovery edges and back edges setLabel(v, VISITED) for all $e \in G.incidentEdges(v)$ if getLabel(e) = UNEXPLORED $w \leftarrow G.opposite(v,e)$ if getLabel(w) = UNEXPLORED setLabel(e, DISCOVERY) DFS(G, w)else setLabel(e, BACK)

### Example



### Example (cont.)



# **DFS and Maze Traversal**

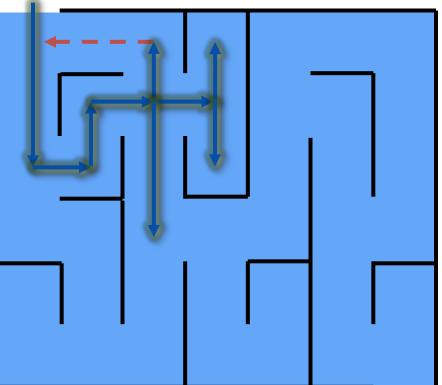
The DFS algorithm is similar to a classic strategy for exploring a

We mark each intersection, corner and dead end (vertex) visited

maze

- We mark each corridor (edge) traversed
- We keep track of the path back to the entrance (start vertex) by means of a rope (recursion stack)

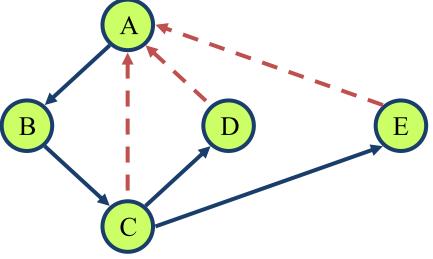




## Properties of DFS

Property 1

**DFS**(**G**, **v**) visits all the vertices and edges in the connected component of **v** 



Property 2

The discovery edges labeled by DFS(G, v) form a spanning tree of the connected component of v

# Analysis of DFS

- Setting/getting a vertex/edge label takes O(1) time
- Each vertex is labeled twice
  - once as UNEXPLORED
  - once as VISITED
- Each edge is labeled twice
  - once as UNEXPLORED
  - once as DISCOVERY or BACK
- Method incidentEdges is called once for each vertex
- DFS runs in O(n + m) time provided the graph is represented by the adjacency list structure
  - Recall that  $\Sigma_{\nu} \deg(\nu) = 2m$

# Path Finding

- We can specialize the DFS algorithm to find a path between two given vertices *u* and *z* using the template method pattern
- We call *DFS*(*G*, *u*) with *u* as the start vertex
- We use a stack *S* to keep track of the path between the start vertex and the current vertex
- As soon as destination vertex *z* is encountered, we return the path as the contents of the stack

Algorithm *pathDFS*(*G*, *v*, *z*) setLabel(v, VISITED) S.push(v)if v = zreturn *S.elements()* for all  $e \in G.incidentEdges(v)$ if getLabel(e) = UNEXPLORED  $w \leftarrow opposite(v, e)$ if getLabel(w) = UNEXPLORED setLabel(e, DISCOVERY) S.push(e) *pathDFS*(*G*, *w*, *z*) **S.***pop*() { *e* gets popped } else setLabel(e, BACK) *S.pop*() { v gets popped }

# Cycle Finding

- We can specialize the DFS algorithm to find a simple cycle using the template method pattern
- We use a stack *S* to keep track of the path between the start vertex and the current vertex
- As soon as a back edge (*v*, *w*) is encountered, we return the cycle as the portion of the stack from the top to vertex *w*

```
Algorithm cycleDFS(G, v)
setLabel(v, VISITED)
S.push(v)
for all e \in G.incidentEdges(v)
   if getLabel(e) = UNEXPLORED
      w \leftarrow opposite(v,e)
      S.push(e)
      if getLabel(w) = UNEXPLORED
         setLabel(e, DISCOVERY)
         cycleDFS(G, w)
         S.pop()
      else
         C \leftarrow new empty stack
         repeat
           o \leftarrow S.pop()
            C.push(o)
         until o = w
         return C.elements()
S.pop()
```