Priority Queues

Priority Queue ADT

- Stores a collection of (key, element) pairs
- Main methods
  - insertItem(k, o): inserts an item with key k and element o
  - removeMin(): removes the item with smallest key and returns its element
  - minKey(): returns, but does not remove, the smallest key of an item
  - minElement(): returns, but does not remove, the element of an item with smallest key
  - size(), isEmpty()

- Applications:
  - Multithreading
  - Triage

Keys must be comparable

- Keys in a priority queue can be arbitrary objects on which a total order relation is defined

- A generic priority queue uses an auxiliary **Comparator ADT**
  - Encapsulates the action of comparing two objects according to a given total order relation
  - The comparator is external to the keys being compared
  - When the priority queue needs to compare two keys, it uses its comparator
    - isLessThan (x,y)
    - isLessThanOrEqualTo(x,y)
    - isEqualTo(x,y)
    - isGreaterThan(x, y)
    - isGreaterThanOrEqualTo(x,y)

Suppose you are given a priority queue implementation, so you have the following operations to work with:

insertItem(k, o)
removeMin()
minKey()
minElement()
size()
isEmpty()

How can you use it to sort a sequence $\boldsymbol{S}$ of numbers?

Sorting with a Priority Queue

We can use a priority queue to sort a set of comparable elements

1. Insert the elements one by one with a series of insertItem(e, e) operations
2. Remove the elements in sorted order with a series of removeMin() operations

Running time depends on the priority queue implementation

Algorithm *PQ-Sort*(*S*, *C*)
Input sequence *S*, comparator *C* for the elements of *S*
Output sequence *S* sorted in increasing order according to *C*
P ← priority queue with comparator *C*
while ¬*S.isEmpty* ()
e ← *S.remove* (*S. first* ())
P.insertItem(*e*, *e*)
while ¬*P.isEmpty*()
e ← *P.removeMin*()
S.insertLast(*e*)

Sequence-based Priority Queue

Implementation with an unsorted sequence

- Store the items of the priority queue in a list-based sequence, in arbitrary order
- insertItem takes $O(1)$ time since we can insert the item at the beginning or end of the sequence
- removeMin, minKey and minElement take $O(n)$ time since we have to traverse the entire sequence to find the smallest key

Implementation with a sorted sequence

- Store the items of the priority queue in a sequence, sorted by key
- insertItem takes $O(n)$ time since we have to find the place where to insert the item
- removeMin, minKey and minElement take $O(1)$ time since the smallest key is at the beginning of the sequence

Selection-Sort

- Selection-sort is the variation of PQ-sort where the priority queue is implemented with an unsorted sequence

- Running time of Selection-sort:
  1. Inserting the elements into the priority queue with n insertItem operations takes $O(n)$ time
  2. Removing the elements in sorted order from the priority queue with n removeMin operations takes time proportional to
     $$1 + 2 + \ldots + n$$

- Runs in $O(n^2)$ time

Insertion-Sort

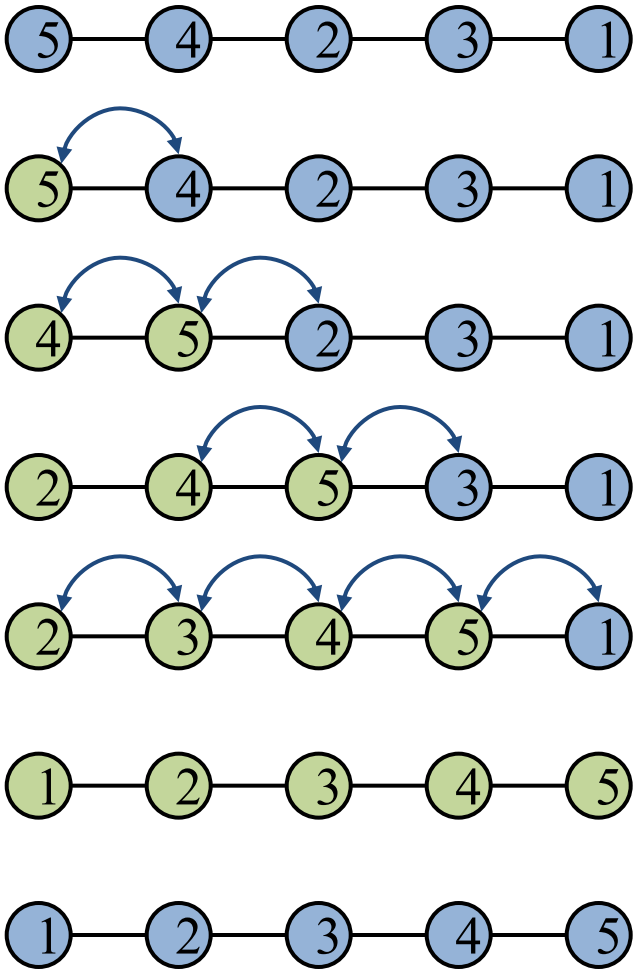
- Insertion-sort is the variation of PQ-sort where the priority queue is implemented with a sorted sequence

- Running time of Insertion-sort:
  1. Inserting the elements into the priority queue with n insertItem operations takes time proportional to
     $$1 + 2 + \ldots + n$$
  2. Removing the elements in sorted order from the priority queue with a series of n removeMin operations takes $O(n)$ time

- Runs in $O(n^2)$ time

In-place Insertion-sort

- Instead of using an external data structure, we can implement selection-sort and insertion-sort in-place
- A portion of the input sequence itself serves as the priority queue
- For in-place insertion-sort
  - We keep sorted the initial portion of the sequence
  - We can use swapElements instead of modifying the sequence

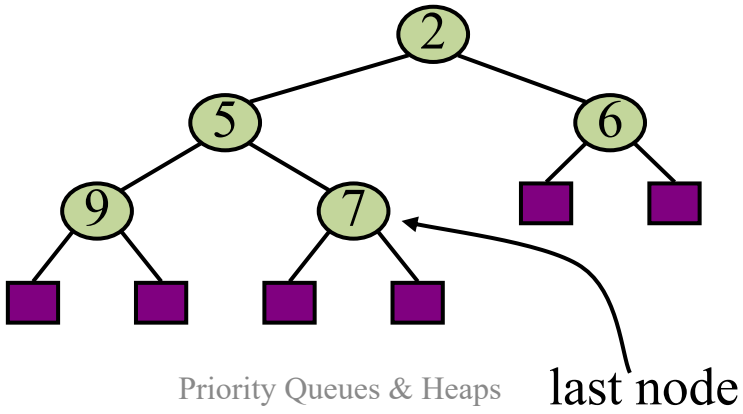


Heap-Based Priority Queue

What is a Heap

- A **heap** is a binary tree storing keys at its internal nodes and satisfying the following properties:
  - Heap-Order: for every internal node v other than the root, $key(v) \geq key(parent(v))$
  - Complete Binary Tree: let h be the height of the heap
    - for $i = 0, \ldots, h - 2$, there are 2^i internal nodes of depth i
    - at depth $h - 1$, the internal nodes are to the left of the external nodes

- The last node of a heap is the rightmost internal node of depth $h - 1$

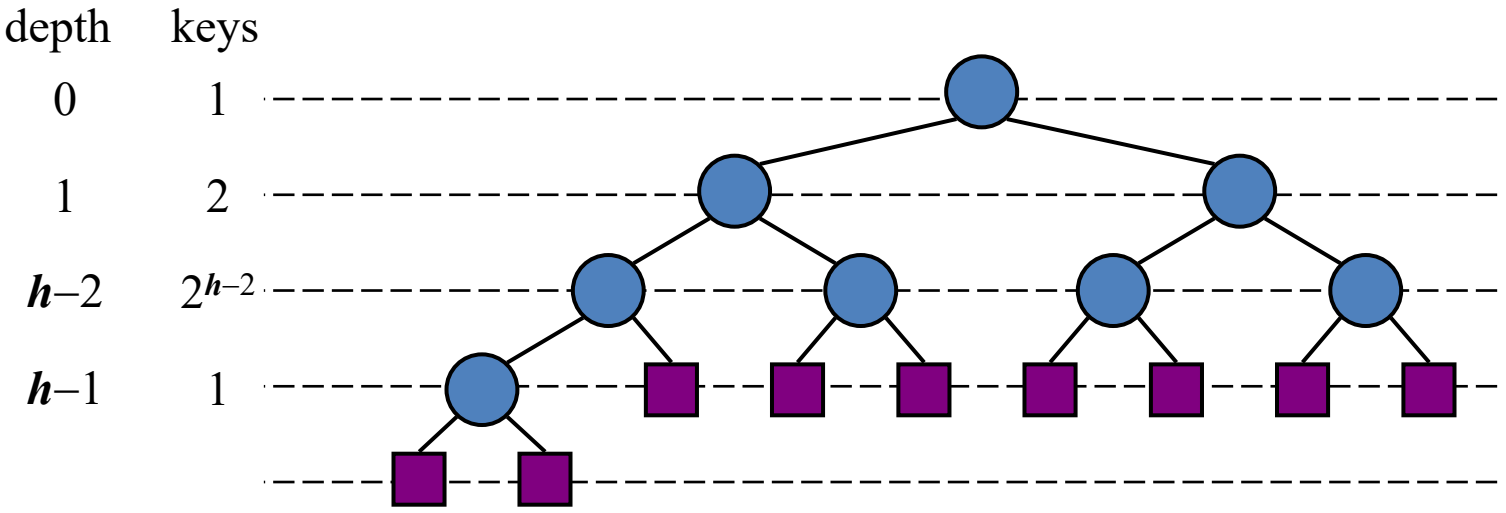


Height of a Heap

Theorem: A heap storing n keys has height $O(\log n)$

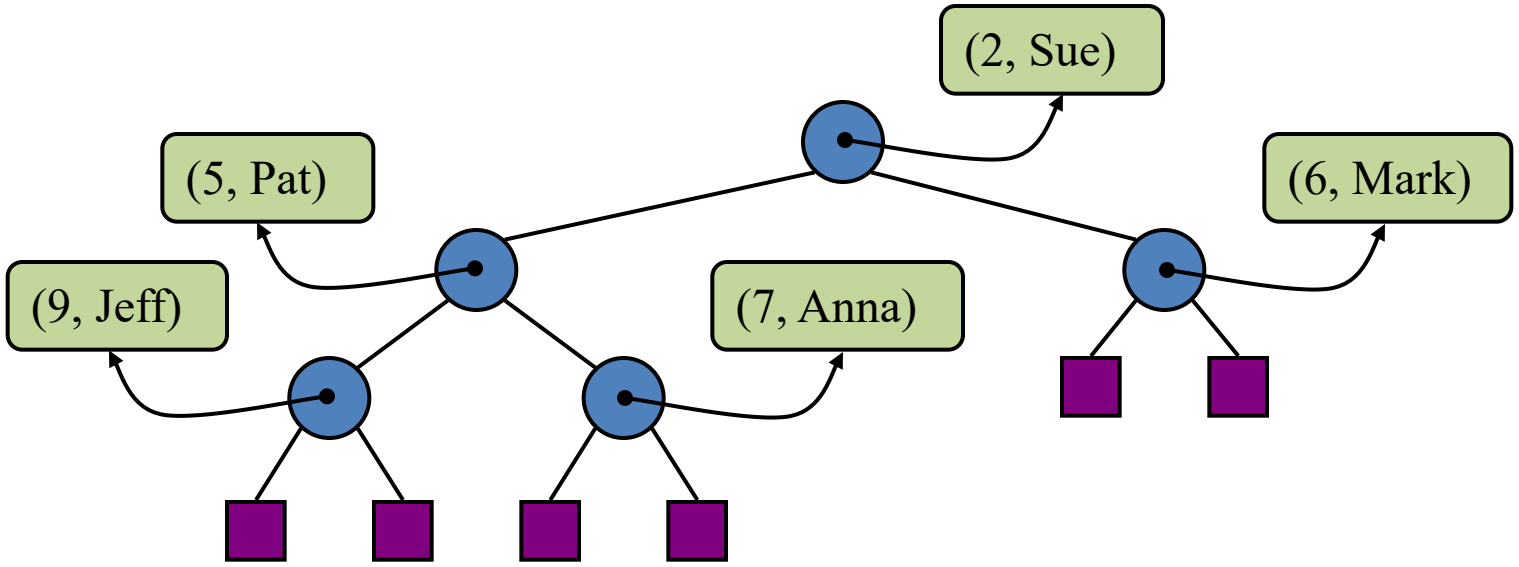
Proof: (we apply the complete binary tree property)

- Let h be the height of a heap storing n keys
- Since there are 2^i keys at depth $i = 0, \ldots, h-2$ and at least one key at depth $h-1$, we have $n \geq 1 + 2 + 4 + \ldots + 2^{h-2} + 1$
- Thus, $n \geq 2^{h-1}$, i.e., $h \leq \log n + 1$



Heaps and Priority Queues

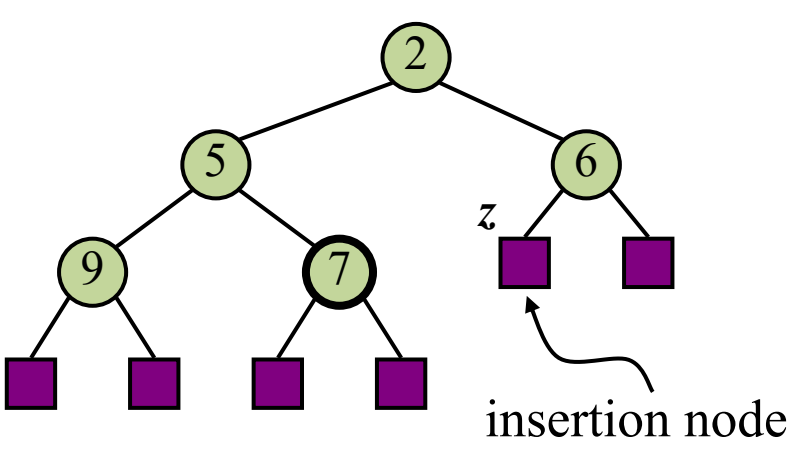
- We can use a heap to implement a priority queue
- We store a (key, element) item at each internal node
- We keep track of the position of the last node
- For simplicity, we show only the keys in the pictures

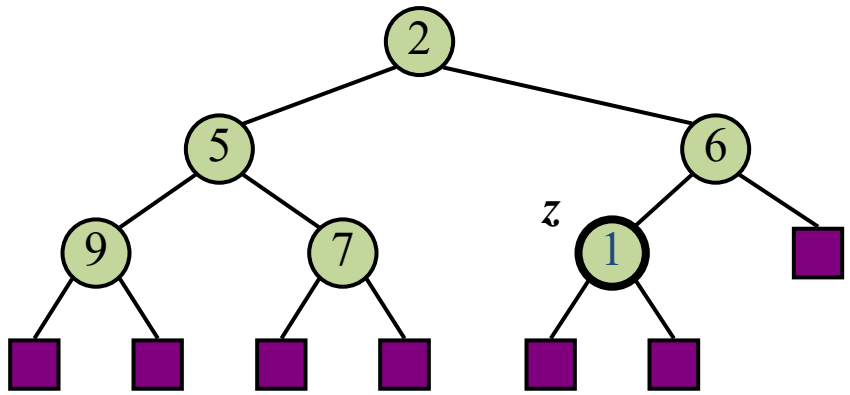


Insertion into a Heap: insertItem(*k*,*o*)

Consists of three steps:

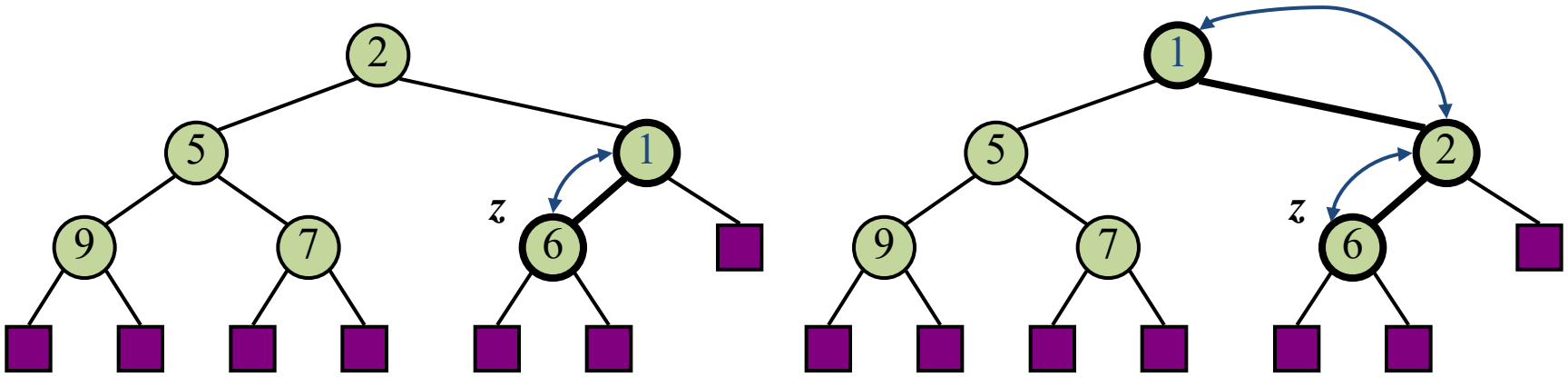
- Find the insertion node ***z*** (the new last node)
- Store ***k*** at ***z*** and expand ***z*** into an internal node
- Restore the heap-order property (discussed next)





Upheap Bubbling

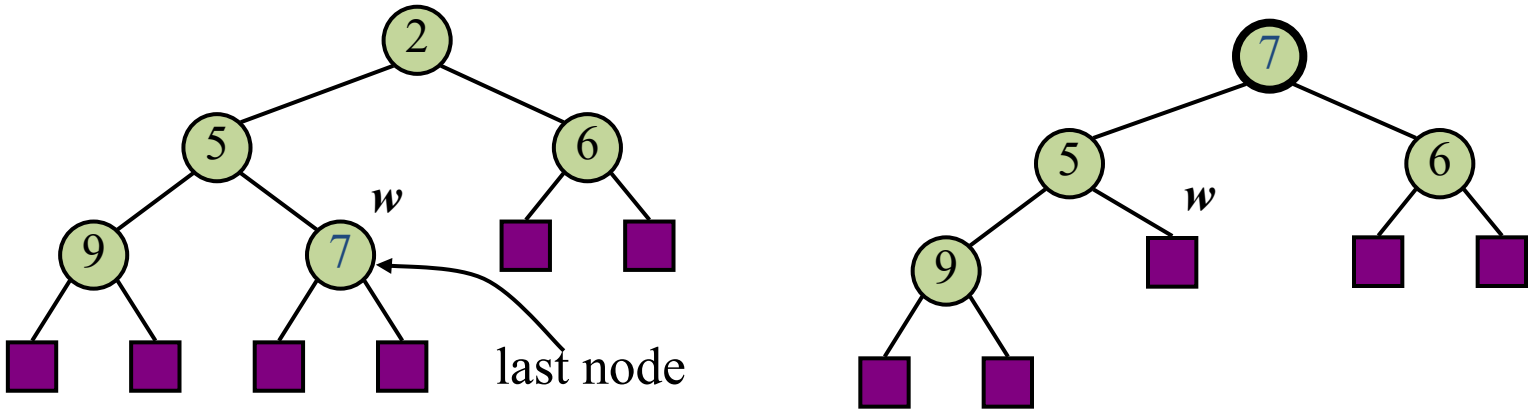
- After the insertion of a new key ***k***, the heap-order property may be violated
- Algorithm upheap restores the heap-order property by swapping ***k*** along an upward path from the insertion node
- Terminates when the key ***k*** reaches the root or a node whose parent has a key smaller than or equal to ***k***
- Since a heap has height ***O***(log ***n***), upheap runs in ***O***(log ***n***) time



Removal from a Heap: removeMin()

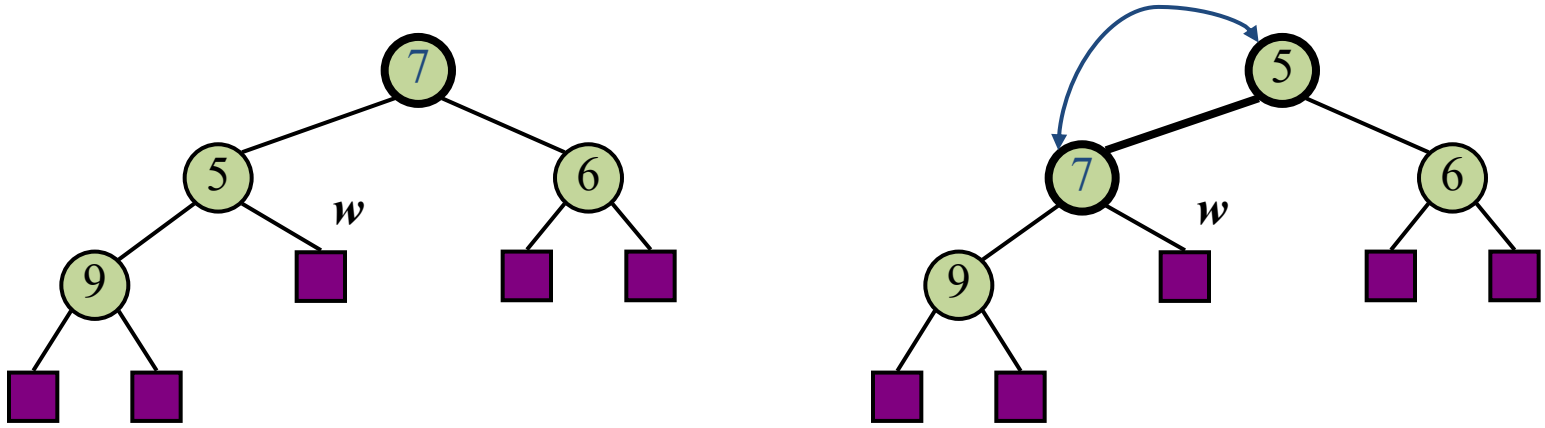
Consists of three steps

- Replace the root key with the key of the last node *w*
- Compress *w* and its children into a leaf
- Restore the heap-order property (discussed next)



Downheap Bubbling

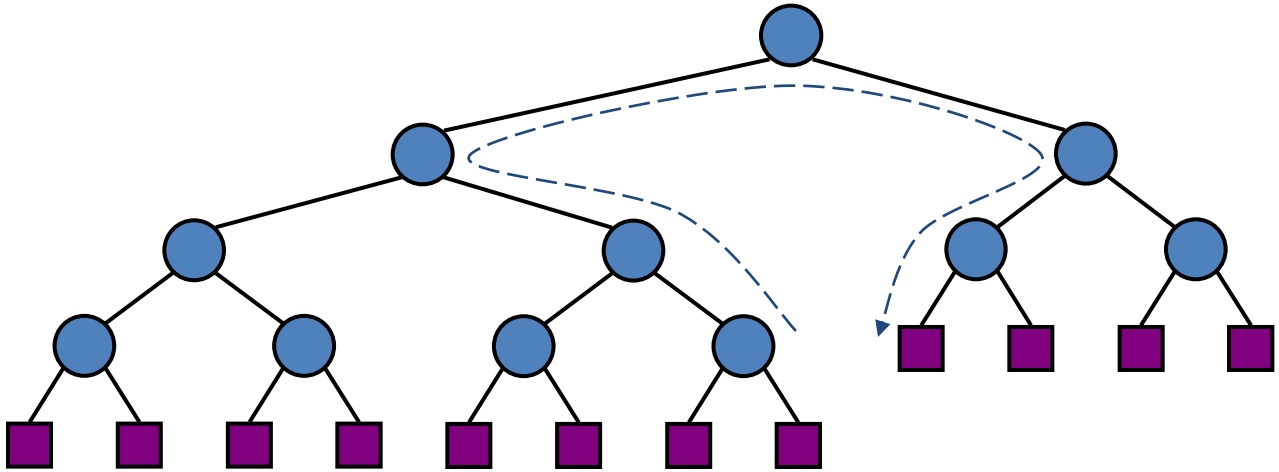
- After replacing the root key with the key k of the last node, the heap-order property may be violated
- Algorithm downheap restores the heap-order property by swapping key k with the smallest key among children along a downward path from the root
- Terminates when key k reaches a leaf or a node whose children have keys greater than or equal to k
- Since a heap has height $O(\log n)$, downheap runs in $O(\log n)$ time



Finding the new Last Node

- The last node can be found by traversing a path of $O(\log n)$ nodes
  - While the current node is a right child, go to the parent node
  - If the current node is a left child of v, go to the right child of v
  - While the current node is internal, go to the left child

- Similar algorithm for updating the last node after a removal



Heap-Sort

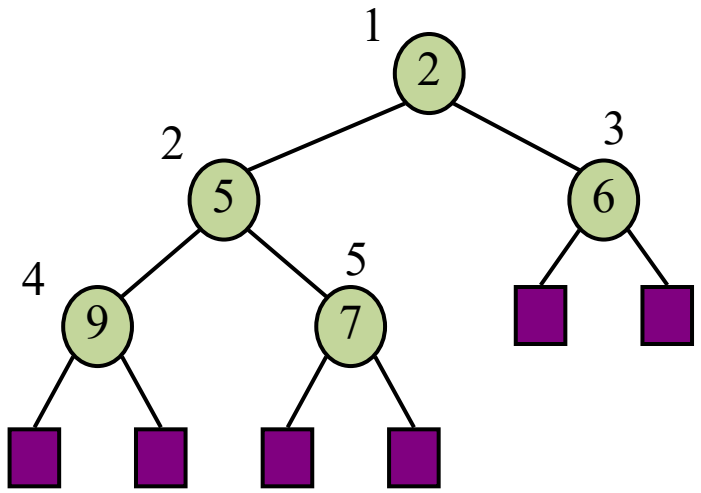
- Consider a priority queue with n items implemented by means of a heap
  - the space used is $O(n)$
  - methods insertItem and removeMin take $O(\log n)$ time
  - methods size, isEmpty, minKey, and minElement take time $O(1)$ time

- Using a heap-based priority queue, we can sort a sequence of n elements in $O(n \log n)$ time
  - much faster than quadratic sorting algorithms, such as insertion-sort and selection-sort

Vector-based Heap Implementation

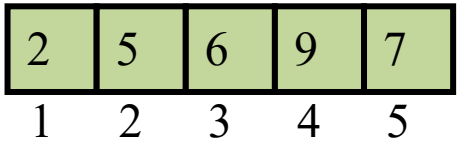
We can represent a heap with n keys by means of a vector of length $n + 1$

- For the node at rank i
  - left child is at rank $2i$
  - right child is at rank $2i + 1$



- What does not need to be stored:
  - links between nodes
  - leaves

- The cell at rank 0 is not used

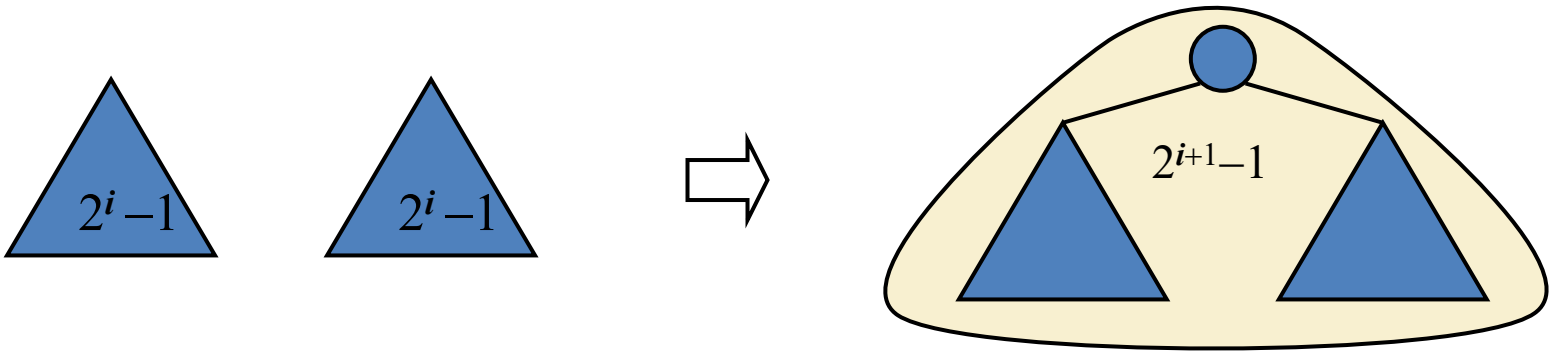


- Last node is at rank n
  - insertItem inserts at rank $n + 1$
  - removeMin removes at rank n (after swapping root with last node)

- Yields in-place heap-sort

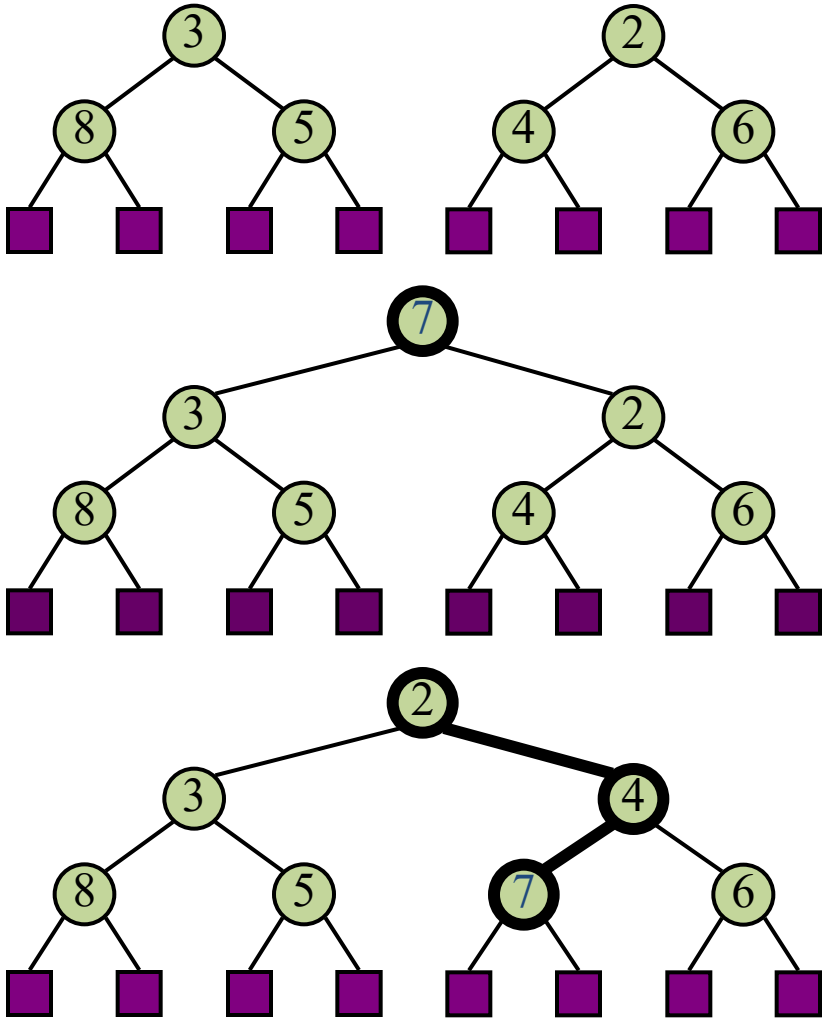
Bottom-up Heap Construction

- If all keys are known in advance, we can build a heap recursively
- For simplicity, assume number of keys $n = 2^h - 1$ so the heap is a complete binary tree, so each depth $i = 0, \ldots, h - 2$ contains 2^i containing internal nodes
- Given n keys, build heap using a bottom-up construction with log n phases
- In phase i, pairs of heaps with $2^i - 1$ keys are merged into heaps with $2^{i+1} - 1$ keys

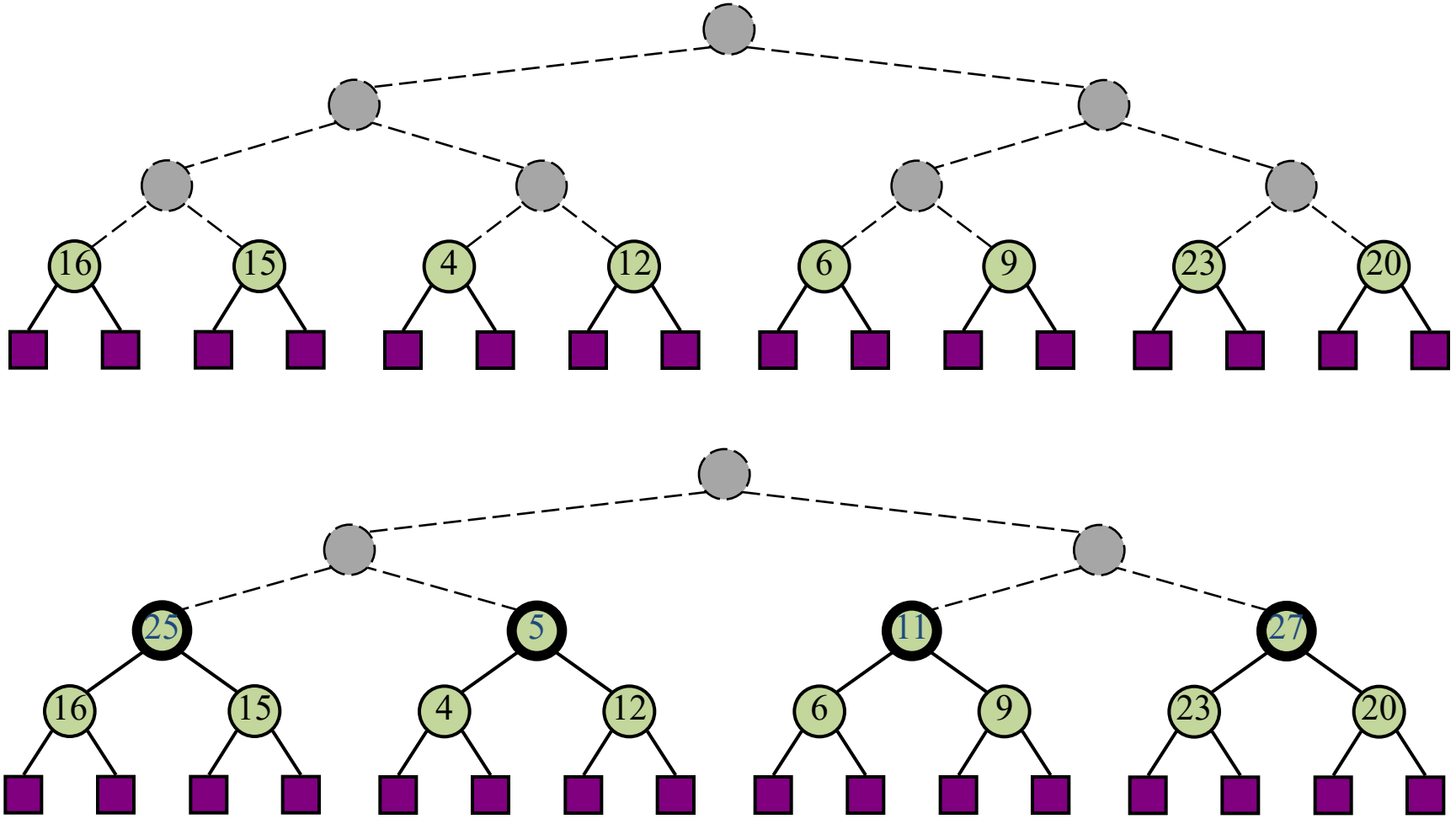


Merging Two Heaps

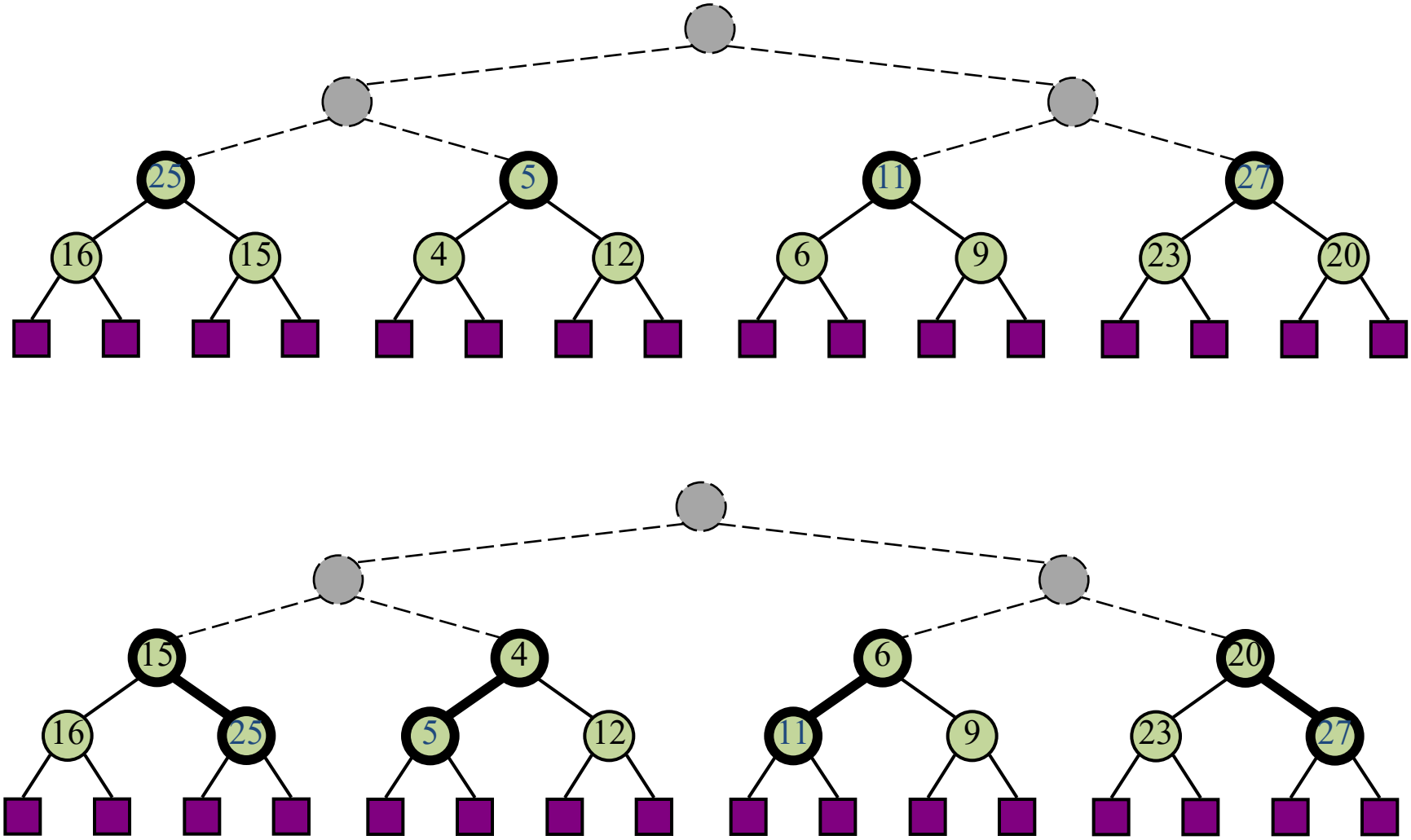
- We are given two heaps and a key k
- We create a new heap with the root node storing k and with the two heaps as subtrees
- We perform downheap to restore the heap-order property



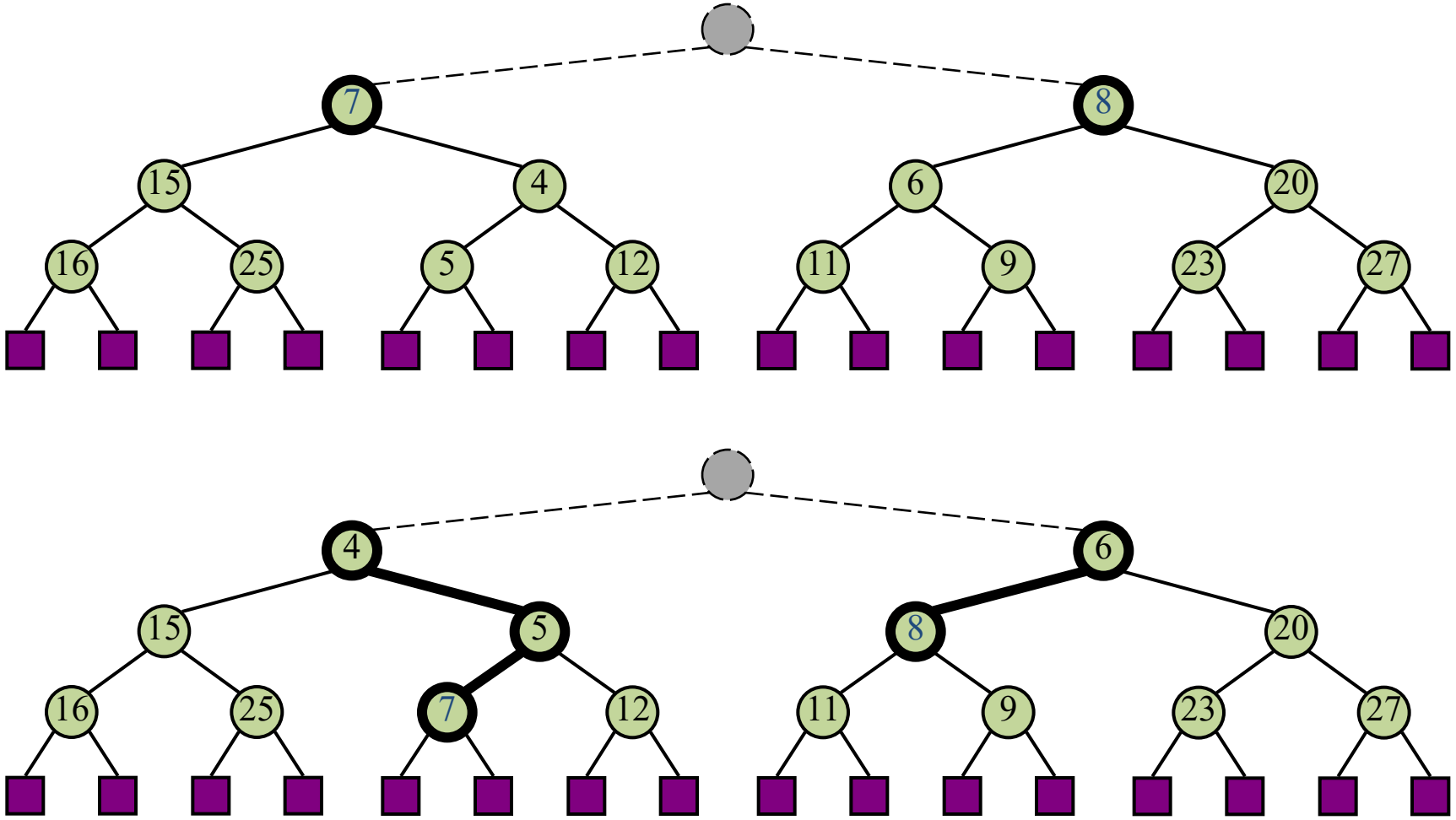
Example



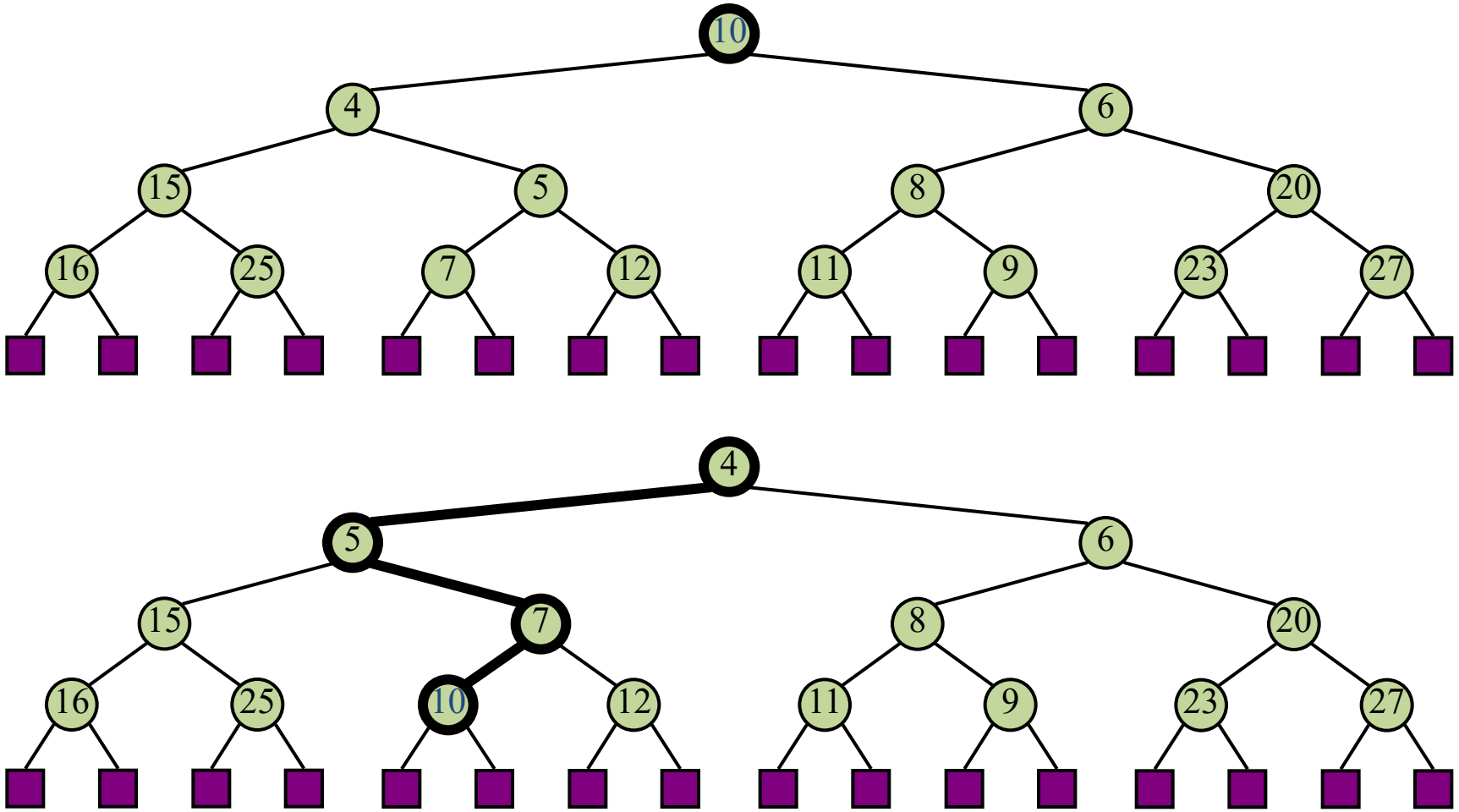
Example (contd.)



Example (contd.)



Example (end)



Analysis

- We visualize the worst-case time of a downheap with a proxy path that goes first right and then repeatedly goes left until the bottom of the heap (this path may differ from the actual downheap path)
- Since each node is traversed by at most two proxy paths, the total number of nodes of the proxy paths is $O(n)$
- Thus, bottom-up heap construction runs in $O(n)$ time
- Bottom-up heap construction is faster than n successive insertions and speeds up the first phase of heap-sort