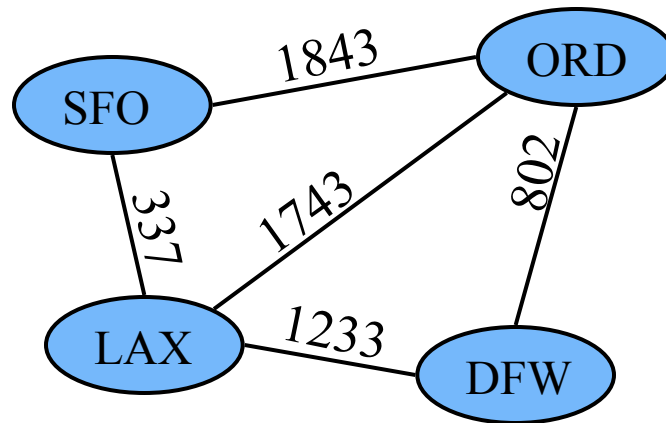


Graphs



Outline / Reading

Graphs (6.1)

- Definition
- Applications
- Terminology
- Properties
- ADT

Data structures for graphs (6.2)

- Edge list structure
- Adjacency list structure
- Adjacency matrix structure

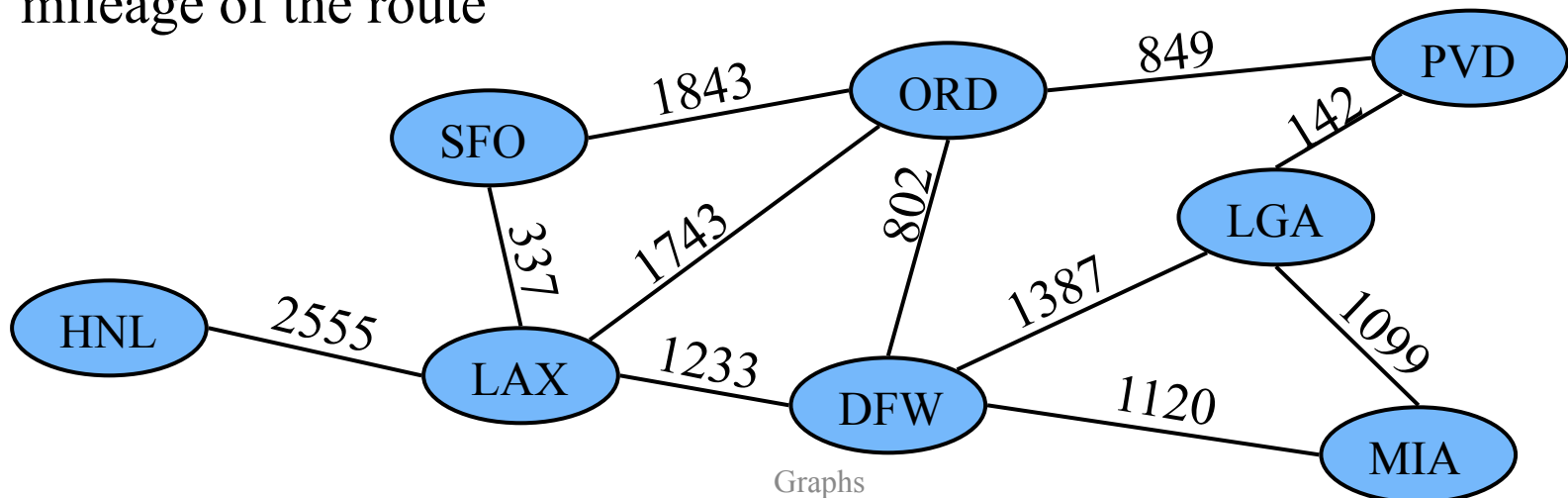
Graph

A **graph** is a pair (V, E) , where

- V is a set of nodes, called **vertices**
- E is a collection of pairs of vertices, called **edges**
- Vertices and edges are positions and store elements

Example:

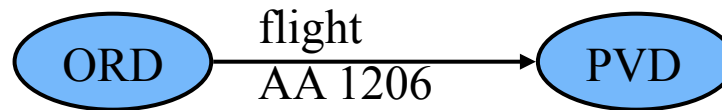
- A vertex represents an airport and stores the three-letter airport code
- An edge represents a flight route between two airports and stores the mileage of the route



Edge Types

Directed edge

- ordered pair of vertices (u, v)
- first vertex u is the origin
- second vertex v is the destination
- e.g., a flight

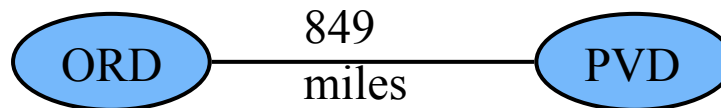


Directed graph

- all the edges are directed
- e.g., flight network

Undirected edge

- unordered pair of vertices (u, v)
- e.g., a flight route

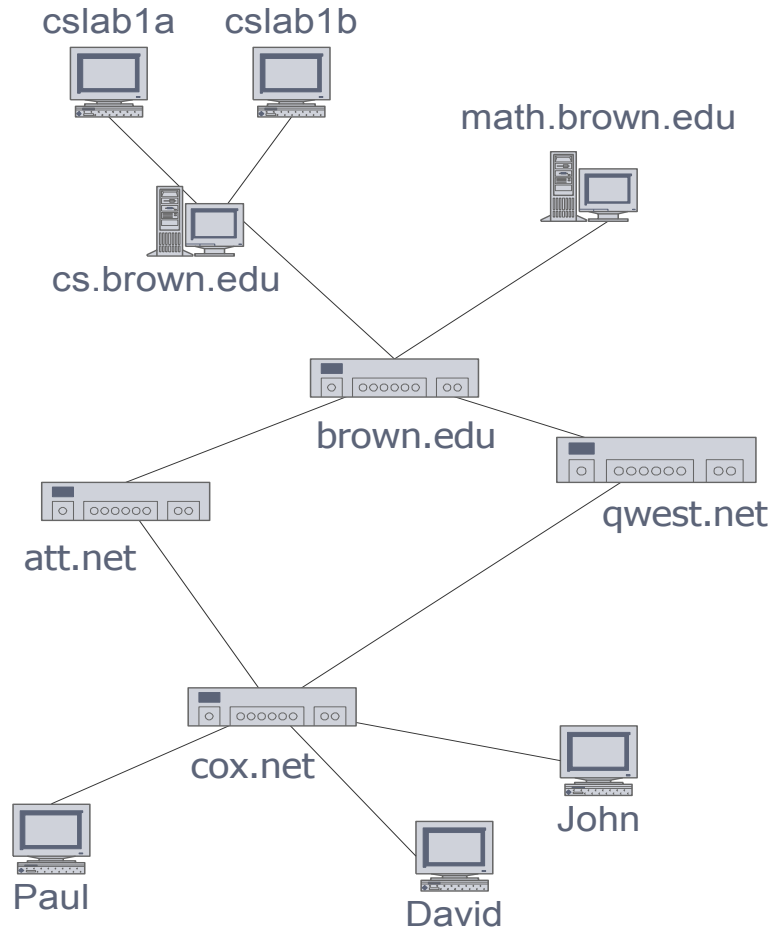


Undirected graph

- all the edges are undirected
- e.g., route network

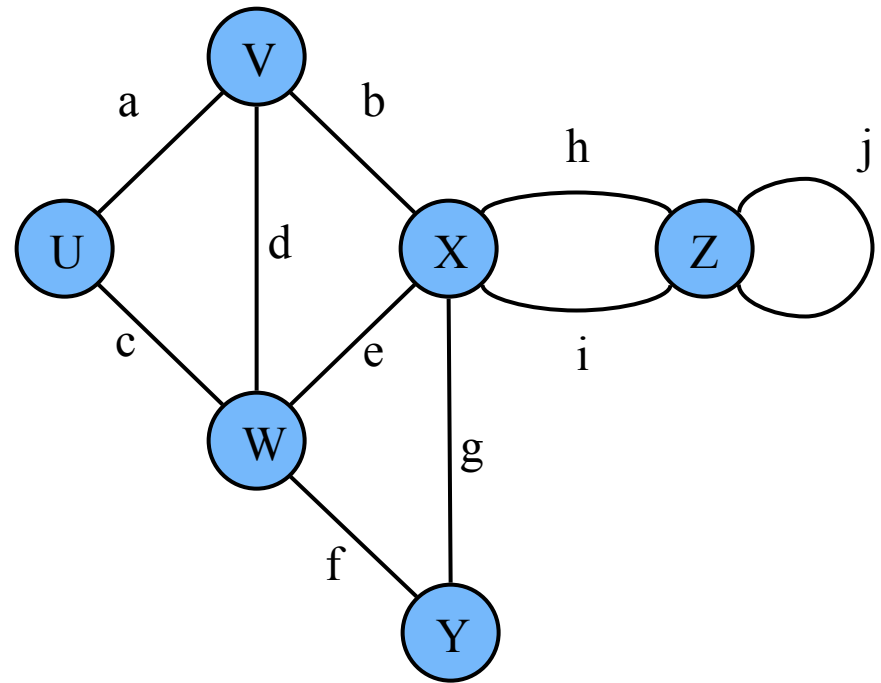
Applications

- Electronic circuits
 - Printed circuit board
 - Integrated circuit
- Transportation networks
 - Highway network
 - Flight network
- Computer networks
 - Local area network
 - Internet
 - Web
- Databases
 - Entity-relationship diagram



Terminology

- End vertices (or endpoints) of an edge
 - U and V are the endpoints of a
- Edges incident on a vertex
 - a , d , and b are incident on V
- Adjacent vertices
 - U and V are adjacent
- Degree of a vertex
 - X has degree 5
- Parallel edges
 - h and i are parallel edges
- Self-loop
 - j is a self-loop



Terminology (cont.)

Path

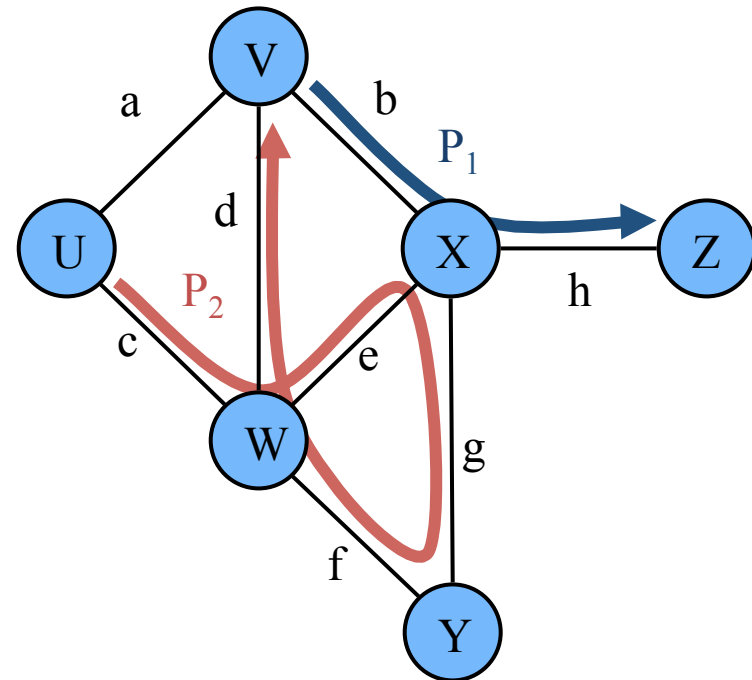
- sequence of alternating vertices and edges
- begins with a vertex
- ends with a vertex
- each edge is preceded and followed by its endpoints

Simple path

- path such that all its vertices and edges are distinct

Examples

- $P_1=(V,b,X,h,Z)$ is a simple path
- $P_2=(U,c,W,e,X,g,Y,f,W,d,V)$ is a path that is not simple



Terminology (cont.)

Cycle

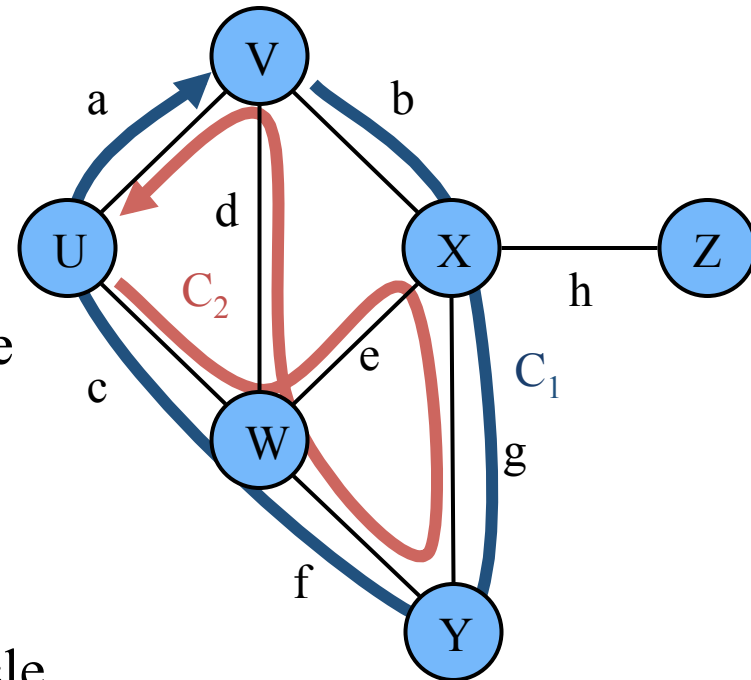
- circular sequence of alternating vertices and edges
- each edge is preceded and followed by its endpoints

Simple cycle

- cycle such that all its vertices and edges are distinct

Examples

- $C_1 = (V, b, X, g, Y, f, W, c, U, a, \curvearrowleft)$ is a simple cycle
- $C_2 = (U, c, W, e, X, g, Y, f, W, d, V, a, \curvearrowleft)$ is a cycle that is not simple



Properties

Notation

n number of vertices

m number of edges

$\deg(v)$ degree of vertex v

Property 1. $\sum_v \deg(v) = 2m$

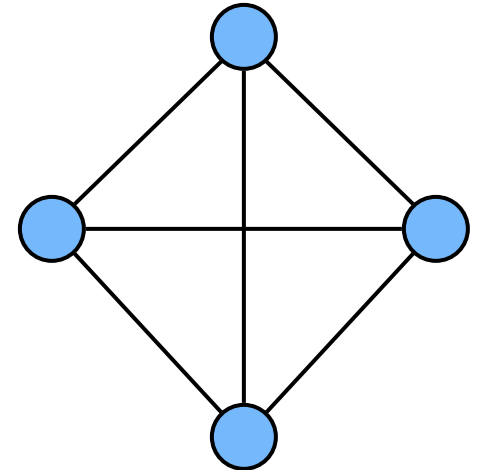
Proof: each edge is counted twice

Property 2. In an undirected graph with no self-loops and no multiple edges

$$m \leq n(n-1)/2$$

Proof: each vertex has degree at most $(n-1)$

What is the bound for a directed graph?



Ex: $n = 4$; $m = 6$;
 $\deg(v) = 3$

Main Methods of the Graph ADT

Vertices and edges

- are positions
- store elements

Accessor methods

- `aVertex()`
- `incidentEdges(v)`
- `endVertices(e)`
- `isDirected(e)`
- `origin(e)`
- `destination(e)`
- `opposite(v, e)`
- `areAdjacent(v, w)`

Update methods

- `insertVertex(o)`
- `insertEdge(v, w, o)`
- `insertDirectedEdge(v, w, o)`
- `removeVertex(v)`
- `removeEdge(e)`

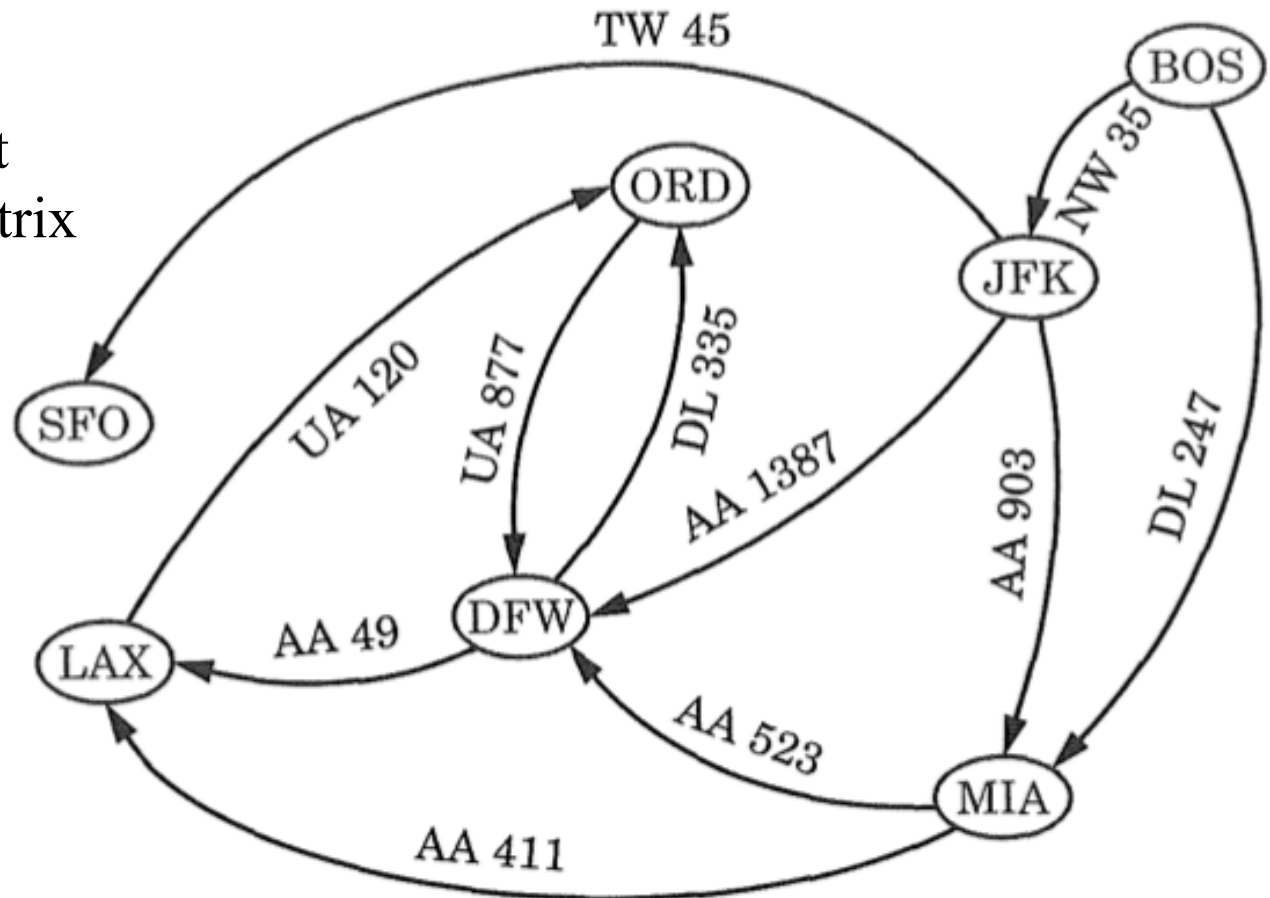
Generic methods

- `numVertices()`
- `numEdges()`
- `vertices()`
- `edges()`

Data Structures

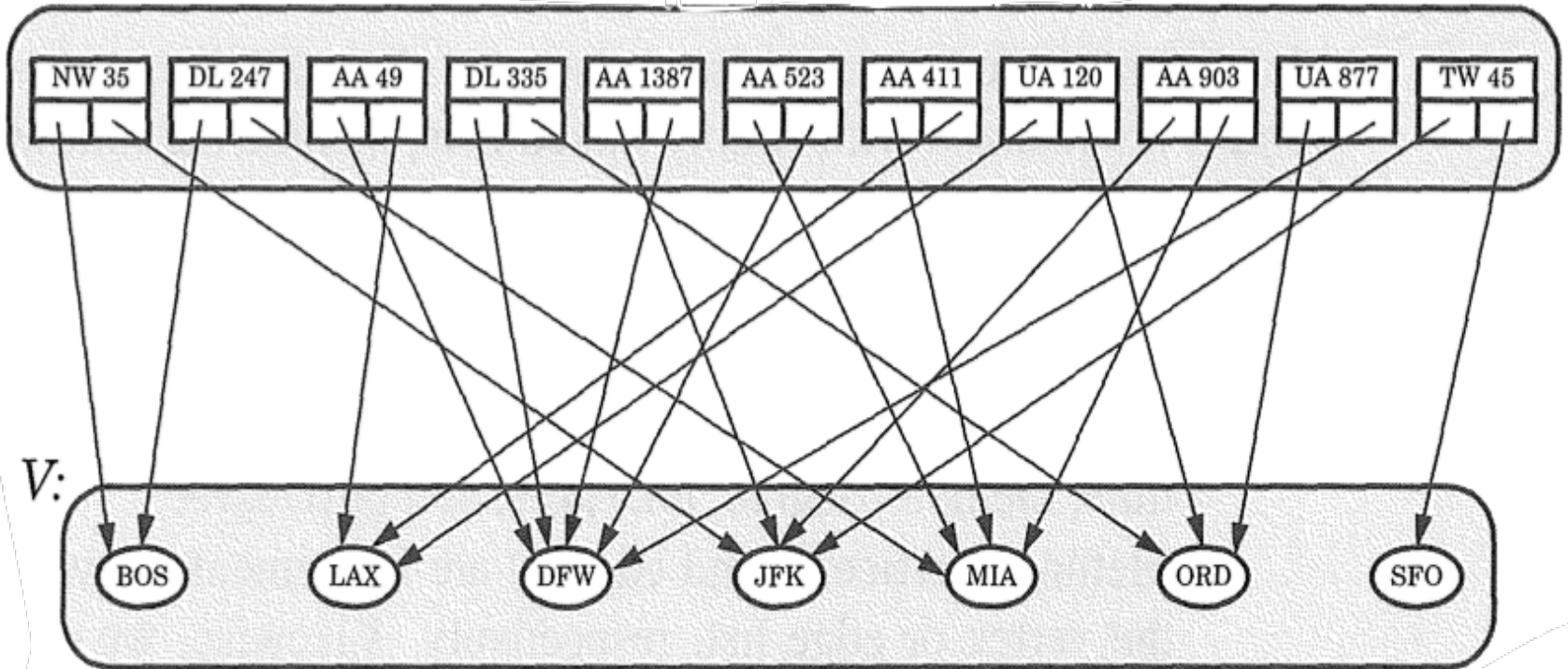
Structures to represent a graph:

1. Edge List
2. Adjacency List
3. Adjacency Matrix



Edge List Structure

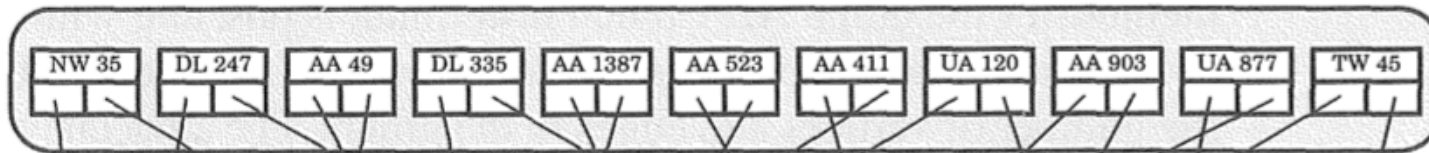
E:



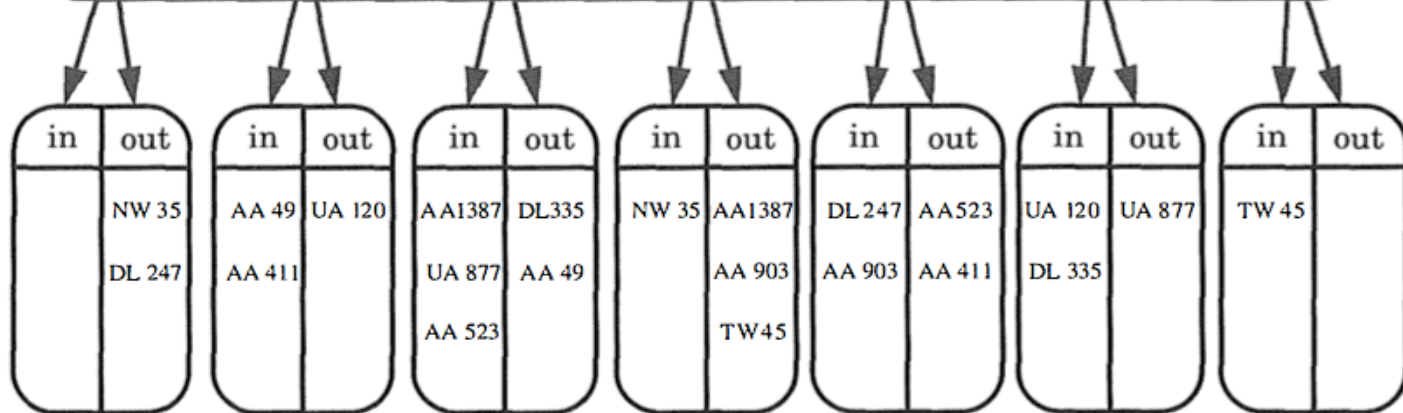
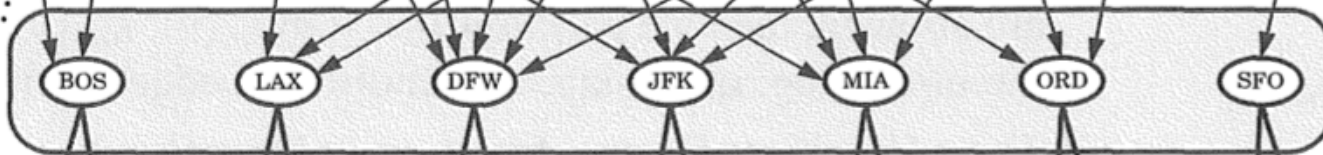
A container of edge objects, where each edge object references the origin and destination vertex object

Adjacency List Structure

E:



V:



An edge list structure, where additionally each vertex object v references an incidence container which stores references to the edges incident on v .

Adjacency Matrix Structure

		0	1	2	3	4	5	6
		BOS	DFW	JFK	LAX	MIA	ORD	SFO
		0	1	2	3	4	5	6
BOS	0	∅	∅	NW 35	∅	DL 247	∅	∅
DFW	1	∅	∅	∅	AA 49	∅	DL 335	∅
JFK	2	∅	AA 1387	∅	∅	AA 903	∅	TW 45
LAX	3	∅	∅	∅	∅	∅	UA 120	∅
MIA	4	∅	AA 523	∅	AA 411	∅	∅	∅
ORD	5	∅	UA 877	∅	∅	∅	∅	∅
SFO	6	∅	∅	∅	∅	∅	∅	∅

A 2D array of all vertex pairs, where cell $A[u,v]$ stores edge e incident on vertices u,v if such an edge exists.

Asymptotic Performance

<ul style="list-style-type: none"> ◆ n vertices, m edges ◆ no parallel edges ◆ no self-loops ◆ Bounds are “big-Oh” 	Edge List	Adjacency List	Adjacency Matrix
Space	$n + m$	$n + m$	n^2
incidentEdges(v)	m	deg(v)	n
areAdjacent (v, w)	m	min(deg(v), deg(w))	1
insertVertex(o)	1	1	n^2
insertEdge(v, w, o)	1	1	1
removeVertex(v)	m	deg(v)	n^2
removeEdge(e)	1	1	1